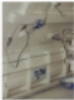


Our robot

With a single line, you can attach a robot to a structure and use it to move objects around. In this case, we use a robot to move a ball around the table. A computer vision system can detect the ball and measure its position and orientation in real-time.



Robot



Our robot

Our robot is a small, white, cylindrical robot with a blue top and a yellow sensor.

- It is controlled by a computer system.
- It has a diameter of 4.5 cm and a height of 10 cm.
- It has a weight of 100 g.
- It has a maximum speed of 10 cm/s.