

S-MASS - SMART LINE CORIOLIS MASS FLOW METER

User Manual







This manual includes the structure, principle, specifications, usage, applicable scope and precautions of the mass flow meter sensor and transmitter developed and manufactured by our company. Be sure to read the manual before installation and operation. For more details about the product, please contact our company.

For maintenance, the primary power supply should be disconnected first.



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1. General

1.1 Introduction

Mass Flow meter is designed according to the Coriolis Principle. It can be widely used for the process detecting in many industries such as petroleum, petroleum and chemical, chemical industry, pharmacy, paper making, food and energy, and so on. As a fairly advanced kind of flow measurement instrument, it has been paid attention by the circle of measurement and accepted by many customers home and abroad.

1.2 Principle

Mass Flow meter is designed according to the principle of Coriolis force. Under the alternating current effect, the magnet and coil installed on the measuring tube will make two parallel measuring tubes vibrate according to some fixed frequency. Once there is flow passing through the pipes, Coriolis force will give rise to deflection (phase shift) on the vibration of two pipes and the deflection of vibration is directly proportional to the mass flow of fluid. Pick up them and the mass flowrate could be calculated.

The vibration frequency of measuring tube is determined by the total mass of measuring tube and inner fluid. When the fluid density changes, the vibration frequency of measuring tube will be also changing, as a result, the fluid density can be calculated.

The temperature sensor installed in the pipeline can pick up the fluid temperature on time under the coordination of measuring circuit.

1.3 Feature

Comparing with the traditional flow measurement method, Mass Flowmeter has following obvious merits:

1.3.1. Enable to measure directly mass flow rate of fluid in the pipeline without changing any parameters, which avoids the some measurement error of intermediate links. Its mass flow rate can be high accuracy and good repeatability within bigger range of turn down ratio.

1.3.2. Fluid measured can be more extensive, such as the steady uniform flow of common viscosity fluid, the high viscosity fluid, non-Newtonian fluid, slurry containing some solid components and the liquid containing some trace of gas.

1.3.3. Due to the small vibration, measuring tube of the Mass Flow meter can be regards as non-moving parts, which will reduce the maintenance of flow meter, enhance the stability and lifetime.

1.3.4. Besides the mass flow measurement, the density and temperature and even consistency can also be picked up and output.

1.4 Measuring system

The measuring system consists of a transmitter and a sensor. Two versions are available:

Compact version: transmitter and sensor form a mechanical unit



Remote version: transmitter and sensor are mounted physically remote from one another

Transmitter

	Two-line display
	Operation with 'Touch control'
29	 Configuration Quick Set up
	 Mass flow, volume flow, density and temperature
	measurement as well as special function(eg, water-cut off)

Sensor

	U series ■ Nominal diameter: 10mm-25mm(3/8"-1") ■ Material: SS316L for measuring tube; SS304 for housing
Ű	U series ■ Nominal diameter:40mm-200mm(1.5"-8") ■ Material: SS316L for measuring tube; SS304 for housing
	 M Series (Micro-bend shape) Nominal diameter:8mm-250mm(1/4"-10") Material: SS316L for measuring tube; SS304 for housing
	 S Series(Super-bend shape) ■ Nominal diameter:50mm-150mm(2"-6") ■ Material: SS316L for measuring tube; SS304 for housing
Case Flow Tube	Drive Coil Pickoff Coil Direction of Flow Arrow Process Connection
 Mechanical parts ar Amplifier works for t 	e the same for U/M/S series sensors the sizes from 100(DN100mm,4") to 300(DN300,12")



2. Technical specifications

2.1 Main Technical Specification

Main Technical Specifications

DN(mm)	8 ~ 250
Medium	Liquid, gas, slurry
Type / Medium Temp.	Integrate type: (-50 ~ 125) °C Remote type: (-50 ~ 200) °C Remote type with high temp.: (-50 ~ 300) °C Remote type with low temp.: (-150 ~ 125) °C
Sensor	Triangle type, U-type, Micro-bend type
Transmitter	DSP
Power Supply	DC24V、AC220V
Output Port	RS485
Pressure (MPa)	1.6、2.5、4.0、6.3; Customized for high pressure: 10.0, 16.0, 26.0
Output Signal	4~20mA, pulse
Accuracy	0.1%, 0.15%, 0.2%, 0.5%
Hygienic Type	Customized
Process Connection	Customized

2.1.1 Flow Range

Table 1: Flo	ow Range	for liquid	U)	Version)	ļ
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DN	Allowable Flow Range (kg/h)	Normal Flow Range for Accuracy 0.1% (kg/h)	Normal Flow Range for Accuracy 0.2% (kg/h)	Normal Flow Range for Accuracy 0.5% (kg/h)	Stability of Zero Point (kg/h)
10	10~1000	100~1000	70~1000	50~ <mark>1000</mark>	0.03
15	20~3000	300~3000	200~3000	150~3000	0.07
25	80~8000	800~8000	600~8000	400~8000	0.15
40	240~32000	2000~32000	1500~32000	1500~32000	0.9
50	$500{\sim}50000$	3500~50000	$2500{\sim}50000$	2000~50000	1.5
80	800~140000	8000~140000	7000~140000	6000~140000	3.5
100	1500~200000	15000~200000	12000~200000	10000~200000	7
150	$5000{\sim}500000$	$50000{\sim}500000$	$35000{\sim}500000$	$28000{\sim}500000$	17
200	10000~1000000	200000~1000000	120000~1000000	80000~1000000	45
300	25000~2500000	50000~25000000	300000~2500000	200000~2500000	70



DN	Max. Flow range (kg/h)	Normal flow range for 0.1% accuracy(Kg/h)	Normal flow range for 0.2% accuracy(Kg/h)	Normal flow range for 0.5% accuracy(Kg/h)	Stability of Zero point (Kg/h)
3	1.2~120	10~120	8~120	6~120	0.004
8	8~800	80~800	55~800	40~800	0.035
10	10~1000	100~1000	70~1000	50~1000	0.045
15	20~3000	300~3000	200~3000	150~3000	0.09
25	80~8000	600~8000	400~8000	300~8000	0.25
40	240~24000	2400~24000	1200~24000	1000~24000	1
50	500~45000	5000~45000	2500~45000	2000~45000	2
80	800~120000	10000~120000	8000~120000	6000~120000	3.5
100	1500~200000	20000~200000	15000~200000	10000~200000	7
150	5000~500000	50000~500000	35000~500000	30000~500000	23
200	10000~1000000	100000~1000000	70000~1000000	50000~1000000	45
250	15000~1500000	150000~1500000	120000~1500000	75000~1500000	70

Table 2: Flow Range for liquid (Micro-bend Version)

Table 3: Flow Range for Super-bend version

DN	Max. Flow range (kg/h)	Normal flow range for 0.1% accuracy(Kg/h)	Normal flow range for 0.2% accuracy(Kg/h)	Normal flow range for 0.5% accuracy(Kg/h)	Stability of Zero point (Kg/h)
50	500~50000	5000~40000	3500~40000	2000~50000	2
80	800~120000	10000~120000	8000~120000	6000~120000	3.5
100	1500~200000	25000~200000	20000~200000	10000~200000	7
150	5000~500000	60000~500000	50000~500000	40000~500000	23

Table 4: Flow range of volume for air under standard temperature and pressure condition (hereafter we call "standard condition")

The flow value of other gas medium =

The value in the below table * Air density under standard condition

DN	Start Flow	Flow Range with Accuracy 0.5%
(mm)	(Nm³/h)	(Nm³/h)
15	12.50	62.5 ~ 2500.0
25	33.33	166.7 ~ 6666.7
40	133.33	666.7 ~ 26666.7
50	208.33	1041.7 ~ 41666.7
80	583.33	2916.7 ~ 116666.7
100	833.33	4166.7 ~ 166666.7
150	2083.33	10416.7 ~ 416666.7

Medium density under standard condition



The volume under working condition can be calculated by the following formula: Volume flow under working condition =

Standard volume flow × $\frac{0.1}{\text{Working Pressure + 0.1}}$ × Working Temperature +273 273

(Note: 1. The unit of working pressure is MPa, the unit of the working temperature is $\ ^\circ\mathbb{C}$.

2. Other gas medium data can be calculated based on above table data * air density under standard condition /medium density under standard condition)

Table 5: Flow rate factor

In many cases, we need to know the flow rate of the medium while using DSP type Mass Flowmeter Mass Flowmeter for gas measurement. The connection size reducing is popular in mass flowmeter gas measurement application, thus the flow rate of Mass Flowmeter Mass Flowmeter (with DSP transmitter) need to be calculated according to the formula below:

Medium Flow Rate = Volume Flowrate under working condition Flow Rate Factor

DN (mm)	15	25	40	50	80	100	150
Flow Rate Factor	0362	1.046	3.535	5.436	15.89	26.15	58.84

Note: 1. The gas flow rate is usually much higher than liquid when measured by flowmeter, so there will be noise caused by gas medium and tube wall of flowmeter under high speed gas flow and if the noise become larger, the signal of flowmeter will be influenced, so **please use Mass Flowmeter for gas medium measurement at speed less than 1/3 of sound velocity!**

2. Please use Mass Flowmeter-Mass Flowmeter for gas with pressure drop not more than 0.2Mpa!

2.1.2 Mass Flow Measuring

2.1.2.1 Flow Range shown in Table 1-4

2.1.2.2 For liquid: Conversion of Basic Error for Mass flow (Table 6)

0.1%	0.2%	0.5%			
±0.1%±(Instant Flow Rate	±0.2%±(<i>StabilityofZeroPo</i> int Instant Flow Rate ×100%)	±0.5%±(<i>StabilityofZeroPo</i> int Instant Flow Rate ×100%)			
Accuracy is calculated based on the water measurement under the condition of +20 $^\circ\mathrm{C}$ \sim 25 $^\circ\mathrm{C}$ and 0.1MPa \sim					
0.2MPa.					

2.1.2.3 Repeatability	(Table 7)
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Accuracy	0.1% for liquid	id 0.2% for liquid 0.5% for both of liquid and				
Repeatability	±0.05% ±0.1% ±0.25%					
Accuracy is calculated based on the water measurement under the condition of +20°C~25°C and						
0.1MPa∼0.2MPa.						



2.1.3 Density Measuring (Table 8)

Density Range	(0.2~3.0)g/cm ³
Basic Error	±0.002g/cm ³ (Affected by the sensor)
Repeatability	0.001g/cm ³

2.1.4 Temperature Measuring (Table 9)

	(-50∼+125) ℃	Integrated Type		
Temperature Range	(-50∼+200)℃ Separate Type			
Basic Error		≤±1.0 ℃		

2.2. Specification of Function

2.2.1 Current Output (Table 10)

Passive 4 to 20mA Current Output can be configured to denote the mass flow or volume flow or density.

Output Range	(4~20)mA				
Resolving Power	0.000244mA				
Basic Error	0.2%F.S				
Temperature Influence	±0.005%F.S/ ℃				
External resistor should be $250{\sim}600\Omega$					

2.2.2 Pulse/Frequency Output (Table 11)

Active Pulse/Frequency Output can be configured to denote the mass flow or volume flow or density.

Output Range	(0~10)kHz				
Resolving Power	0.152Hz				
Basic Error	±0.075%				
Temperature Influence	±0.001%F.S/ ℃				
Capability of Outrange is 12kHz					

2.2.3 RS485 Output

RS485-Modbus-RTU is optional for each set Mass Flowmeter.

2.2.4 Low Flow Cutoff

When the flow value measured is lower than the value of Low Flow Cutoff, the Mass Flowmeter will output zero flow and the totalizer will stop to accumulate. The value of Low Flow Cutoff is usually sets to be 1% of the maximum flow rate.

2.3 Environment Limitation

2.3.1 Environment vibration (Table 12)



Frequency Range	(10∼2000)Hz		
Acceleration amplitude	2g		
value			
Circulation time	50 times		

2.3.2 Environment temperature (Table 13)

Working Temperature	(-40∼+55)°C
Storage Temperature	(-20∼+70) ℃

2.3.3 Environment humidity (Table 14)

Working Humidity	<90%	+25 ℃
Storage Humidity	<95%	No condensation

2.3.4 Enclosure Grade: IP65

2.4. Outline Dimension (See the following Drawings and Tables)

Ð DN (10~25) DN (40~200) Separate Version **Compact Version Compact Version** L H1 Code DN L1 Н Separate ≤ 4.0MPa ≥6.3MPa Integrate

Dimensions of U tube







Drawing 5: Micro-bend Version

Dimensions of Micro-bend type

Mass		L		14		H1	
Flowmeter	DN	≤ 4.0MPa	≥6.3MPa		п	Integrate	Separate
008	8	424	484	302	154	270	185
010	10	424	484	302	154	270	185
015	15	400	414	280	191	298	213
025	25	500	536	360	258	302	218
040	40	600	634	460	306	315	230
050	50	800	828	640	410	325	240
080	80	900	928	700	495	350	265
100	100	1130	1156	860	665	370	285
150	150	1410	1450	1200	905	400	316
200	200	1800	1844	1450	1175	426	342
250	250	1966	2006	1530	1300	468	383







Unit: mm

Drawing 6: Super-bend Version

Mass	DN			11	Ц	H1	
Flowmeter	DN	≤ 4.0MPa	≥6.3MPa		11	Integrate	Separate
050	50	800	834	588	200	330	250
080	80	935	973	730	200	355	270
100	100	1130	1182	870	275	370	290
150	150	1370	1410	1070	378	400	330





Drawing 6: Dimensions for separate type transmitter (unit: mm)

2.5. Weights

able 15: net weights Onit: kg						iit: kg			
DN (mm)	10	15	25	40	50	80	100	150	200
Triangle and U type	10	13	17	30	40	100	190	325	536
Micro-bend type	8	12	15	25	38	78	135	265	430

Note: transmitter for separate type is 5kg.

3. Introduction

3.1 About This Manual

This manual mainly introduces the installation, connection, startup, operation, and trouble-shooting of Mass Flowmeter. The user must read this manual carefully before use, because improper installation may cause incorrect measurement and even damage the flowmeter.

3.2 Safety

- **3.2.1** Please ensure that the power goes off to avoid the accident of electric shock when assembling a transmitter.
- **3.2.2** Please defer to the way of installation and usage to ensure the normal operation of the flowmeter.

3.3 Components

Mass Flowmeter is made up of sensor and transmitter, which can be installed integrally or separately. When Mass Flowmeter is installed separately, the sensor and transmitter should be connected through special Nine-Core Cable.



3.4 Installation Process

- **3.4.1** Step 1: Location: Determine the installation location of sensor, which should take the installation area, pipeline, transmitter location and valve into account.
- **3.4.2** Step 2: Direction: Determine the installation direction of sensor in the pipeline.
- **3.4.3** Step 3: Installation: Install the sensor and transmitter in the pipeline.
- **3.4.4** Step 4: Connection: When Mass Flowmeter is installed separately; the sensor and transmitter should be connected through special Nine-Core Cable.
- **3.4.5** Step 5: Start-up.

4. Installation

- 4.1 Position selection
 - **4.1.1** The sensor should be placed away from interference source which may cause pipe's mechanical vibration such as the pump along the process pipeline. If sensors are used in series along the same line, care must be taken to guard against the mutual influence due to resonance. The distance between sensors should be at least more than three times its width.
 - **4.1.2** When installing the sensor, pay attention to the expansion and contraction of the process pipeline due to temperature change. It is strongly recommended that the sensor should not be installed near the expansion joint of the process pipeline. Otherwise, the pipe expansion and contraction of the pipeline will bring about transverse stress which can affect the sensor's zero, as a result of which the measurement accuracy will be affected.
 - **4.1.3** The sensor should be placed away from industrial electromagnetic interference sources such as large power motors and transformers, otherwise, the measuring tube's auto-oscillation within the sensor will be interfered, and the weak signal detected by the speed sensor may be drowned by the electromagnetic noise. Therefore, the sensor should be away from such sources as motors and transformers, at least five meters.
 - **4.1.4** The sensor should be placed in the position where its measuring tube is always filled with fluids and a certain pressure out is maintained, thus it should be placed in the lower end of the pipeline.
 - **4.1.5** Basic requirement: Install the Mass Flowmeter in the lower position of the pipeline so that the fluid can fill with the sensor during the process of zero point calibration and running. The transmitter should be installed in the environment with temperature from -40~+55℃ and humidity <90%.
 - **4.16** Straight pipe: Mass Flowmeter does not require the special straight pipe upstream or downstream. However, if tow or more mass flow sensors are installed serially in the same pipeline, please ensure the length of pipe between any two sets is more than 2 meters.



4.1.7 Maximum length of cable: (shown in Table 15)

Cable Model	Cable Specification	Max. Length
Special Nine-Core Cable	Special	300m
Current Power Line	18AWG(0.8mm2)	300m
RS485 Communication Line	22AWG(0.35mm2)	300m

4.1.8 Working temperature of sensor: (shown in Table 16)

Integral Type	(-50∼+125)℃
Separate Type	(-50∼+200)°C
High temperature Separate Type	(-50 \sim +300) $^\circ\!\!{ m C}$ under developing
Low temperature Separate Type	(-150 \sim +125) $^\circ\!\!\mathbb{C}$ under developing

4.1.9 Valve: It is necessary to carry through zero point calibration once the installation of Mass Flowmeter is finished. The downstream stop valve has to be close at first before zero point calibration, and then close the upstream stop valve.

4.2 Direction

4.2.1 Basic requirement:

The Mass Flowmeter works well only when the liquid fills with the measuring tube. In principle, as long as the measuring tube is full of liquid, the Mass Flowmeter will function in any orientation installation. Generally speaking, the Mass Flowmeter is installed in the orientation which makes the liquid fill with the measuring tube.

For the horizontal installation, the measuring tube should be installed underside the pipeline when the process medium is liquid or slurry (shown on Picture 1) and topside the pipeline when the process medium is gas (shown on Picture 2). For the vertical installation, the measuring tube should be installed besides the pipeline when the process medium is liquid or slurry or gas (shown on Picture 3).



4.2.2 Flow direction:

There is obvious flow arrow which indicates the proper flow direction on the front of the sensor, so please install the Mass Flowmeter according to it. Otherwise, the transmitter may not display the mass flow normally.

For vertical installation, if the process medium is liquid or slurry, the flow direction is down-to-up; if the process medium is gas, the flow direction can be either



down-to-up or up-to-down. The transmitter can be mounted with 90° revolution according to the requirement of installation.

4.3 Sensor Installation

4.2.3 Basic requirements:

The installation of the Mass Flowmeter should decrease the tortuosity of the process connection. Meanwhile, do not support the pipeline by the sensor of the Mass Flowmeter. (Shown in Picture 4)

4.2.4 Installation of the Mass Flowmeter-150 Sensor: It is better to support the sensor of Mass Flowmeter using rubber connector as the buffer.

Overview of the transmitter (Same for both integrate & remote type)



4.4 Wiring

-0-	3
	2
	4

Thread form + Threads Thread **Position of thread** Pitch No. quality of pitch length engaged (1) Case Thread on front cover Medium, 6h 25mm 2mm ≥6 (1) Front cover Thread on front cover 2mm Medium, 6H 25mm ≥6 (2) Case Thread on back cover Medium, 6h 2mm 25mm ≥6 (2) Back cover Thread on back cover 2mm Medium, 6H 25mm ≥6 Thread for cable gland (3) A/F 1.814mm Medium, 6H 15mm ≥ 6 1/2" NPT Thread for case (4) A/F1.5 Medium, 6H 26mm >6

4.4.1 Wiring for Coriolis mass flowmeter S-MASS

4.4.1.1Specifications for wiring cables

Cables must fulfill the requirements set forth in EN/IEC 60079-14.

The wiring cables of the flowmeter are divided into three parts: nine-core shielded cable, power cable and output cable. The specifications are as follows, shown in Table below.



Table Cable specification				
Cable Model	Cable Specification	Max. Length	Gland type	Position of Use
Nine-Core shielded cable	Only provided	≤100m	NPT 1/2"	
		AC85∼250V power supply,≤300 m	M20×1.5	
Power cable	1∼2.5 mm²	DC 18∼30V power supply,≤100 m	NPT 1/2"	
Output cable	20AWG(0.5mm ²)	Pulse output, ≤100 m	NPT 1/2"	Ass formetr
		(4 ~ 20)mA current output, ≤500m		



4.4.1.2. Wiring of integrated flow meter

Using the matched gland NPT 1/2", choose the appropriate inner diameter of rubber sealing ring according to the diameter of the power cable. And using a three-core power cable, the cross-sectional area of the single wire is about $1\sim 2.5$ mm².



Fig.4.3 The operation of gland

Pass the power cable through the parts of the gland in order according to the wiring method in Figure 4.3. Then pass one end of the power cable through the right interface of the transmitter, fixed the power cable with a screwdriver according to the instructions on the power wiring board, as shown in figure 4.4. After installation, tighten the clamping nut with a wrench to complete the power cable connection, as shown in figure 4.5, and applied 13.0N.m torsion to the clamping nut to tighten it.







Fig.4.5 The installation of power cable



Operate as above, complete the signal line access. The wiring after installation is shown in figure 4.6.



Fig.4.6 The wiring of transmitter

NOTE: If the S-MASS (DN≥100) is installed, it is required that the drive-amplifier of sensor is supplied with power connection.

4.4.1.3. Wiring of Remote flow meter

If the sensor of S-MASS is installed separately with the transmitter, the nine-core shielded cable is required to connect with transmitter and sensor, which will be provided by SMERI. The wiring of the remote transmitter power cable is the same with the compact type transmitter, but the connection to the sensor still requires a 5m dedicated nine-core cable, as shown in figure 4.7.



Fig.4.7 The connection of split transmitter and sensor If a longer dedicated nine-core cable is required, please contact SMERI.

4.4.1.4.Nine-core shielded cable connection

Cut off the power supply before installing the nine-core shielded cable.Stripped about 60mm of cable jacket. Remove the filling material between the metal foil and the wire around the insulated wire, retained a length of about 10mm metal foil, and separate the wires. Combined the shield wires and wrapped twice on the exposed foil. Remove the insulation from each wire end, the stripped cable is as



shown in figure 4.8.



Fig.4.8 The stripped cable

Pass the cable through the gland and the adapter, split terminal box wiring port, the wire ends are crimped according to the color of the cable on the corresponding terminal block. Connect the combined shield wires to the grounding screw of the junction box, as the figure 4.9 shows.



Fig.4.9 Nine-core shielded cable connection

The bending radius of the nine-core shielded cable is greater than or equal to 120mm.



Fig. 4.10 Nine-core shielded cable connection



Caution

_ . .

Cut off power before connecting cables. The power voltage must match that indicated in the junction box of the transmitter and the earth connector must be well connected with earth wire to ensure its intrinsic safety performance.

. ...

Table 4.1 Nine-core cable color and function				
Wire No.	Wire Color	Function		
1	Brown	The left coil+		
2	Red	The left coil-		
3	Orange	The right coil+		
4	Yellow	The right coil-		
5	Green	Driving coil+		
6	Blue	Driving coil-		
7	Gray	Temperature+		
8	White	Temperature-		
9	Black	Temperature compensation		

4.4.1.5. Installation of remote mass flow meter

The mass flow transmitter should be installed in the range of:

temperature (-20 ~ +55), humidity ≤90%. Remote-type mass flow transmitter can be placed on a flat surface, according to the installation needs, and adjust the installation angle.

4.4.1.6. Grounding

Both of the sensor and the transmitter have to be ground correctly, otherwise the measurement error will occur and even the S-MASS may not work. If the pipeline is connected with the ground, the transmitter can be earthed through the pipeline; if the pipeline is not connected with the ground, the transmitter should be earthed independently.

The ground wire is as short as possible, impedance is less than 1 Ω . The cross-sectional area of the internal ground wire must be greater or equal to the power cable. Internal grounding reference identification operation as show in figure 4.12.

In figure 4.12 a, for transmitter, S-MASS had used a wire (cross-sectional area 2.5mm²) connected the internal ground screw to the pin 'FG' of power terminal, and user just need to tighten the ground wire of three-core power cable to the power terminal as figure 4.11.

In figure 4.12 b, twist the shielded wire of the nine-core wire and connected it to the internal grounding insert. And in figure 4.12 c, use one of the three-core power cable as a ground wire connected to the insert.

The cross-sectional area of the external grounded wire must be ≥ 4 mm², and the external grounding position is shown in figure 4.13 below.





a. The internal ground of transmitter



b. The internal ground of split-type



blit-typec. The internal ground of drive-amplifierFig. 4.12Internal grounding



b. The external ground of split-type



a. The external ground of transmitter





c. The external ground of drive-amplifier Fig. 4.13 External grounding

Specific grounding method can refer to the corresponding national standard or follow the use of factory standards.

4.5 Start-up

4.5.1 Zero-point calibration

Please see **6.5.1** for details.

4.5.2 Instrument coefficient

Each set of the Mass Flow meter has its own instrument coefficients, which have been set before delivery. So the user does not need to set instrument coefficient except either the sensor or the transmitter is replaced. All the coefficients which can are typed on the name plate. Generally, the sensor and the transmitter are in couples, and the coefficient has been input into the transmitter. The meter can be used without additional change.

5. Power Supply and Signal output Wiring

5.1. Power wiring

5.1.1 The basic requirement:

The transmitter can be connected to the AC220V or the DC24V power.

AC (85 to 265) V	Power Consume: Normal	10 W, MAX 15W
DC (18 to 30) V	Power Consume: Normal	10 W, MAX 15W

5.1.2 Power Cable

The power cable should choose 2-core cable and the area of each core >0.8 square millimeter. For AC220V, the length of the power cable should be \leq 300m, for DC24V, the length of the power cable should be \leq 100m.





DC Power Wiring for DSP transmitter

- 5.2 4-20mA output wiring
 - **5.2.1** 4~20mA Passive output can be configured to mass flow or volume flow.
 - **5.2.2** The cable should choose 2-core cable and the area of each core > 0.5 square millimeter.





Figure 5.2

5.2.3 4~20mA current output terminal block.

- I+ is the current input of the Mass Flowmeter;
- I- is the current output of the Mass Flowmeter;

The illustration is in Figure 1:



Figure 5.3

5.2.4 Active Output and Passive Output

Active Output is that the current output is powered by the Mass Flowmeter itself. Only the sampling resistance is needed while collecting the current output signal. The illustration is in Figure 2:





Passive output is that besides the sampling resistance, the outer power supply of 24VDC must be added so as to get the current output from the mass flowmeter. The illustration is in Figure 3:



Figure 5.5

5.2.5 The Switch between Passive Output and Active Output

The switch between passive current output and active current output is realized by setting the jumpers of J6 on the output board.





If active current output is required, we need to short-circuit jumper 1 and 2, then jumper 3 and 4 as well. The illustration is in Figure 4:



Figure 5.6

If passive current output is required, we need to short-circuit jumper 2 and 3. The illustration is in Figure 5:



Figure 5.7

Active and passive current output

- Active current output is that the devices such as transmitters and signal generators have already been supported by power supply circuit of their own, so the 4~20mA signal could be directly output from the positive and negative terminal blocks, forming a signal circuit with the signal collecting device, which could measure the signal directly in this way.
- Passive current output is that the devices like the transmitters and signal generators have no supporting power supply circuit of themselves. Only when the signal collecting device could provide additional power supply to them, the 4~20mA signal could be output to be measured by the signal collecting device.

5.3 Pulse output wiring

- **5.3.1** Active pulse output can be configured to mass flow or volume flow or density. The output cable should be 2-core cable and the area of each core is > 0.5 square millimeter.
- **5.3.2** The length of output line should be \leq 150m.





5.4 RS485 output wiring

RS485 output obeys MODBUS protocol. The length of output line should be \leq 300m.



5.5 Amplifier wiring

For the sensor size over 100mm(4"), it needs additional the power supply for the amplifier, which is the same power type with sensor. The power could be AC(85~260)V or DC(18~36)V. Please double check the power type in the nameplate on the sensor. For AC220V, the length of the power cable should be \leq 300m, for DC24V, the length of the power cable should be \leq 100m, and choose 2-core cable and the area of each core >0.8 square millimeter. Pic 3-6 for the wiring.



Picture 3-6 Wiring for amplifier

6. Operation

6.1 General

Please use the operation panel of transmitter to set the configuration, such as basic configuration parameters, zero calibration, cutoff value of low flow and output range of current frequency, etc.

The panel of the transmitter is shown as below:





No.	Notes
1	E key: enter
2	\rightarrow key: move curse or return
3	↓ key : page down
4	Light for working status
5	Two line OLED

6.2 Key Function

Key	Measurement State	Menu State	Function State	Data State
	Show the measurement results and state on Page1/2/3. Page down to menu state.	Next Menu	Select Function	Change number Change unit Change character
\rightarrow	Return to the last screen	Return to the upper-level menu, press the key several times to return to the measurement state	Select Function	Move the cursor right
E		Enter the Menu	Confirm and Save the function	Save the input, choose Yes or No, then back to function menu



Note 5: Operation point of Photoelectric Key is located right behind the glass panel. It is better to operate the photoelectric key in vertical direction, rather than horizontal direction.

6.3 Measuring Value Checking





6.4 Configuration Parameter

Please review or set the configuration parameters according to the following indications (press \blacksquare to page down and press \blacksquare to move the position of cursor or return):



6.4.6 Pulse/Frequency Output



1) Set Pulse Equivalent
 Configuration → E → PassWord? (Default password is 000000) → I → Output Config → E → Pulse Weight
 → E → Set Pulse Equivalent.

Set Pulse Signal

Configuration → E → PassWord? (Default password is 000000) → I → Output Config → E → Pulse Weight
 → Pulse Output → E → Set the pulse output signal as mass flow (Default), volume flow, density or water content.

6.4.7 RS485 Output Configuration → E → PassWord? (Default password is 000000) → [] → Output Config → E → Pulse Weight → [] → Pulse Output → [] → 20mA Value → [] → Current Output → [] → MODBUS Address (Set the MODBUS adress) → [] → Baud Rate (Set the baud rate) → [] → Parity Bit (Set the parity bit) → [] → Stop Bits (Set the stop bits)

6.4.8 First Menu

First menu: The screen will automatically display the content chosen in "First menu" if the no key operation happened to the transmitter within 128 seconds.

 Configuration
 → E → PassWord?
 (Default password is 000000)
 → II → Output Config
 → II → Unit Config

 → II → PressureComp
 ↓ → Other
 → E → Output AUTO Sim
 → FlowSimulate
 → II → Flow Sim Start

 → II → First Menu
 ▲ E → Set the "first menu" as Mass(Mass interface), Volume(Volume Interface) or not change (The screen will not automatically switch to any other interface)

6.4.9 Oil and Water Content Analysis

 Configuration
 → E → PassWord?
 (Default password is 000000)
 → I → Output Config
 → I → Unit Config

 → I → PressureComp
 → Other
 → Addons Function
 E → OW AnalyseSwitch
 (Set it as "on" to enable this function)

 → I → Other
 ↓ → Addons Function
 E → OW AnalyseSwitch
 (Set it as "on" to enable this function)

 → 20 °C OilDen g/mL
 (Set the density of the water in the mixture)

6.4.10 Zero Calibration



6.5 Calibration

Generally speaking, the Mass Flow meter does not need the field calibration for the user because it has been calibrated before delivery.

Each set of Mass Flow meter has its own instrumental coefficient, including one flow coefficient and four density coefficients (high density D1, high period K1, low density D2 and low period K2), which will be shown in Nameplate of Sensor.

The sensor and transmitter are usually delivered as a pair and instrumental coefficient has been set in transmitter so the user does not need to change any longer.



6.5.1 Zero Calibration

Zero calibration provides the datum mark of flow meter for flow measurement. It is necessary to carry through zero calibration when the Mass Flow meter is finished to install for the first or a second time.

After correct installation, the Mass Flow meter should be powered at least 30 minutes for warm-up and then make the liquid pass through the flow meter until the temperature of Mass Flow meter is same as working temperature of liquid. Afterward, close the downstream valve, make the liquid pass through the flow meter under normal temperature, density and pressure and then close the upstream valve to assure the sensor is full of liquid during the process of zero calibration.

Finally, press \rightarrow Configuration \rightarrow Zero-Cal \rightarrow Flow configuration \rightarrow Zero Correction \rightarrow E \rightarrow Input password to start zero calibration.

6.5.2 Flow Calibration

The mass measured by the Mass Flow meter is resulted from the multiplication of detected signals' time difference between two circuits and flow calibration factor. When the accuracy is not up to grade after long-term service, please modify the flow calibration factor according to the following formula:

K1=K0×[1+(M-Mt) / Mt]=K0×M/Mt

Note:

- K1 New flow calibration factor,
- K0 Old flow calibration factor,
- M Total mass flow of Master Meter,
- Mt Total mass flow of Tested Meter.

7. Pressure Drop

Pressure drop of flow meter is the unrecoverable pressure loss resulting from the resistance of the flow. The flow path of the mass flow meter is relatively complex and always with reducing pipe. So the pressure drop is a very important factor and can't be ignored.

Pressure drop of mass flow meter is dependent upon the fluid characteristics, the flow state and the structural parameters of the sensor. When the fluid density, viscosity and flow rate are fixed, the pressure drop is only relevant to the structural factors of the sensor part, such as diameter, cross-sectional area of the flow tube, flow tube shape etc.

The reducing pipe is inevitable for the design and manufacture of the mass flow meter. The total cross-sectional area of the two flow tubes is less than the cross-sectional area of the flange. Thus the velocity increases when the fluid enters the mass flow meter. The maximum flow velocity is a very important factor for the industrial control, and the



flow velocity affects the technological process and safety etc. As a result, some users may have the requirement of the upper limit of the flow velocity.

When the viscosity is between two adjacent Pressure Drop lines, the Pressure Drop can be calculated with following formula:

$$\Delta P = \Delta P_1 + \frac{\Delta P_2 - \Delta P_1}{\mu_2 - \mu_1} \times (\mu - \mu_1)$$

Note: the mass flow value should be converted to the volume flow value.

The pressure drop of Mass Flow Meter can be checked from following Pressure Drop Chart (including Pressure Drop, flow, and viscosity parameters). Please contact factory for the detail sizing calculation by providing the fluid name, viscosity, density, flow range.





























8. Trouble Shooting

8.1 Overview

During the first installation and use, if there is something abnormal related to the working of flowmeter, generally speaking, it should be resulted from either the application or the flowmeter system. Application is usually complex, which involves the measurement error of fluctuation caused by technology, change of medium, so it should be analyzed according to the actual application while this chapter mainly focuses on the causes and solutions of flowmeter system malfunctions.

8.2 Diagnostic Tool

For the flowmeter fault diagnosis, the user can judge by the LED indicator and LCD displays, LED lights of different colors and brightness contrast on the panel, which represent the working condition of flowmeter. Meanwhile, LCD displays can show the self-diagnostic alarming information of the transmitter, which is favorable for user's judgment and defining the malfunctions.

In addition, it is necessary to use handheld digital multimeter when testing the static resistance values and cables of the sensor.

8.3 Sensor

When testing the malfunction of the flowmeter, first of all, detect the coils resistance of sensor according to Table 13 and check if their values are fallen within the normal range.



Loop	Line color	Sensor port	Normal resistance range
Left coil	Brown, red	1, 2	(20~100)Ω
Right coil	Orange, yellow	3, 4	(20~100)Ω
Drive coil	Blue, green	5, 6	(2~110)Ω
Temperature	Gray, white	7, 8	(75~175)Ω
Temperature	Gray, black	7, 10	(75~175)Ω



8.4 Power and connection

The first installation of electricity, power should be checked to ensure that effective the following elements:

Choose the correct voltage for power supply, connect the power cable correctly, open insulating layer of two ends of the cable and pinch them firmly;

Power cable should be not connected with same output port of Mass Flowmeter Transmitter with signal cables of input/output;

Transmitter should be earthed firmly and the earth resistance should be less than 1 Ω , (use the copper wire with area more than 2.5 mm2).

8.5 LED-Indicator

The proportion of light and dark shown by LED indicator represents the working condition of the flowmeter.

LED condition	Working condition
Always light at beginning	Impassable self-test
Always light afterward	Wrong zero-calibration
Light for 1/4second, dark for 3/4 second	Malfunction alarm
Light for 3/4second, dark for 1/4 second	Slug flow excesses



9.6 The cable jacket can be divided into two kinds of $\phi 8.5$ and $\phi 12$ according to the inner hole of cable gasket ring while the outside diameters of cables are respectively $\phi 8 \sim \phi 8.5$ and $\phi 8.5 \sim \phi 12$. Please change the cable and gasket ring once aging or wearing out.

9.7 Be sure that there is no gases which erode aluminum alloy.

9.8 Be sure that the maintenance or repair should be in safe place without flammable gases.

9.9 The correspondences between working temperature of medium and maximum surface temperature of flow meter body are as follows:

	Т3	Τ4	T5	T6
Working temperature	200°C	135℃	100°C	85℃
Surface temperature	195℃	130°C	95℃	80°C



Note: 1. This menu chart can only be applied to Digit Mass Flowmeter Program Ver2.55 and later version



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SMERI s.r.l. Via Mario Idiomi 3/13 I 20090 Assago MI Tel. +39 02 539 8941 Fax +39 02 539 3521 E-mail: smeri@smeri.com www.smeri.com



